

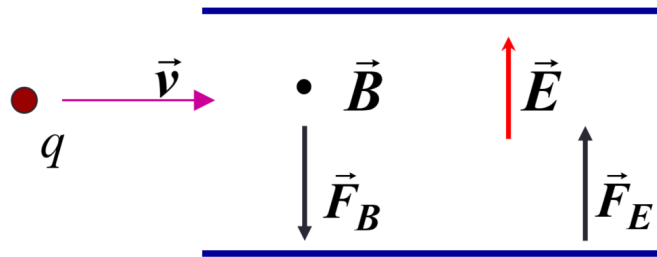
ELECTRICITY AND MAGNETISM (PHYS 231)

Lecture 16: Magnetic Field & Magnetic Forces

Oct 23, 2024

Velocity Selector

If a charged particle q is experiencing both \vec{E} and \vec{B} : $\vec{F} = q\vec{E} + q\vec{v} \times \vec{B}$



If $q > 0$, then the magnetic force will be downwards and the electric force will be upwards.

It is possible to achieve a perfect cancellation between magnetic & electric forces.

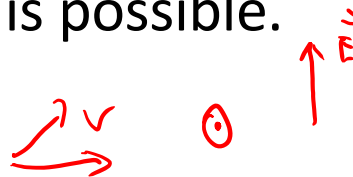
$$qE = qvB \quad \longrightarrow \quad v = \frac{E}{B}$$

Velocity selector: only particles with the right velocity can pass!

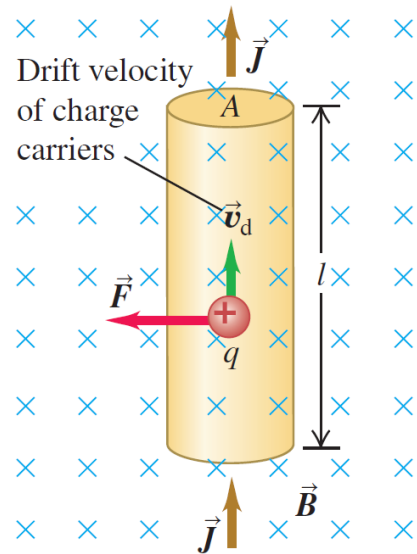
A charged particle moves through a region of space that has both a uniform electric field and a uniform magnetic field. In order for the particle to move through this region at a constant velocity,

- A. the electric and magnetic fields must point in the same direction.
- B. the electric and magnetic fields must point in opposite directions.
- C. the electric and magnetic fields must point in perpendicular directions.
- D. more than one of A, B, or C is possible.

✓ E. not enough information



Magnetic Force on a Current-Carrying Wire



We start with a wire of length l and cross section area A in a magnetic field of strength B with the charges having a drift velocity of v_d .

If the charge density is n , the total charge in this wire is nAl .

The magnetic force on a single charge is qv_dB .

The total force on the wire is $F = qv_dBnAl = (nqv_d)AlB$

$$I = JA = (nqv_d)A$$

$$F = IlB$$

Magnetic force on a straight wire segment $\vec{F} = I\vec{l} \times \vec{B}$ Magnetic field

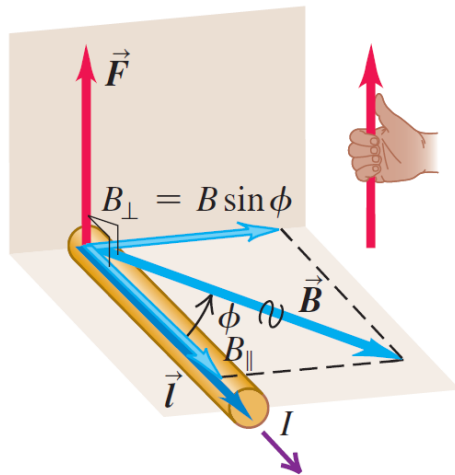
Current

Vector length of segment (points in current direction)

Magnetic Field

Force \vec{F} on a straight wire carrying a positive current and oriented at an angle ϕ to a magnetic field \vec{B} :

- Magnitude is $F = I l B_{\perp} = I l B \sin \phi$.
- Direction of \vec{F} is given by the right-hand rule.



Magnetic force on a straight wire segment $\vec{F} = I \vec{l} \times \vec{B}$ Magnetic field

Current

Vector length of segment (points in current direction)

- The force is **ALWAYS** perpendicular to both the wire & the magnetic field.
- The direction of \vec{F} is determined by the **right-hand** rule.

Warning: Use your right hand even if you are left-handed.

Example

A wire 20.0 cm long lies along the z-axis and carries a current of 5 A in the +z-direction. The magnetic field is uniform and has components $B_x = -0.2$ T, $B_y = -0.9$ T, and $B_z = -0.3$ T.

Find the magnetic force on the wire and its magnitude.

$$\vec{F} = I \vec{l} \times \vec{B} \quad \vec{l} = 0.2 \text{ m } \hat{k} \quad \vec{B} = -0.2 \hat{i} - 0.9 \hat{j} - 0.3 \hat{k}$$

$$= (5 \text{ A} \cdot 0.2 \text{ m}) \hat{k} \times (-0.2 \hat{i} - 0.9 \hat{j} - 0.3 \hat{k}) \text{ T}$$

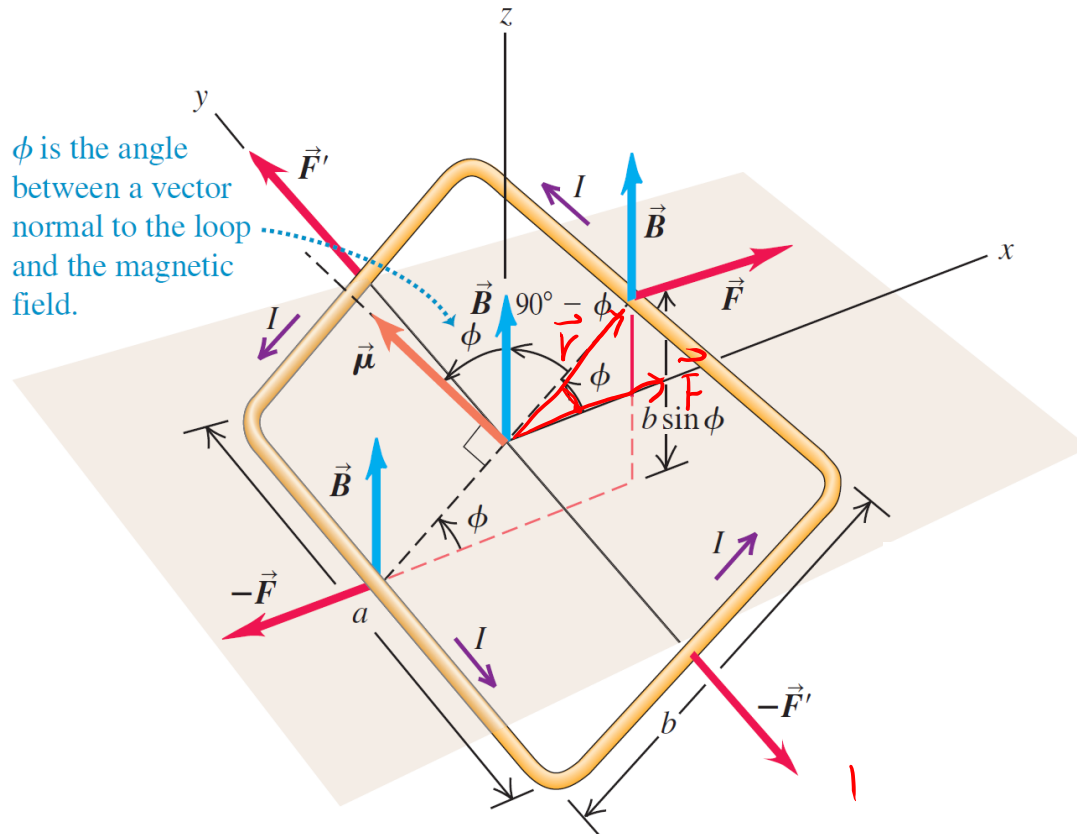
$$= (1 \text{ A} \cdot \text{m}) (-0.2 \hat{j} + 0.9 \hat{i}) \text{ T}$$

$$= (+0.9 \hat{i} - 0.2 \hat{j}) (\text{A} \cdot \text{m}) \text{ T}$$

$$\left\{ \begin{array}{l} \hat{k} \times \hat{i} = \hat{j} \\ \hat{k} \times \hat{j} = -\hat{i} \\ \hat{k} \times \hat{k} = 0 \end{array} \right.$$

$$|\vec{F}| = \sqrt{(0.9)^2 + (0.2)^2} = \sqrt{0.81 + 0.04} = \dots$$

Current Loop in a Magnetic Field



The **net force** on a current loop in a uniform magnetic field is **zero**.

However, the **net torque** is **not** in general equal to zero.

$$F = IaB, \quad F' = IbB\cos\phi$$

Torque: $\vec{\tau} = \vec{r} \times \vec{F} = rF\sin\phi$

The **lever arm** for each force is $\frac{b}{2}\sin\phi$

The net torque is $\tau = 2F \left(\frac{b}{2}\right) \sin\phi = \underline{IBab \sin\phi}$

Magnetic Dipole/Moment

Magnitude of magnetic torque on a current loop

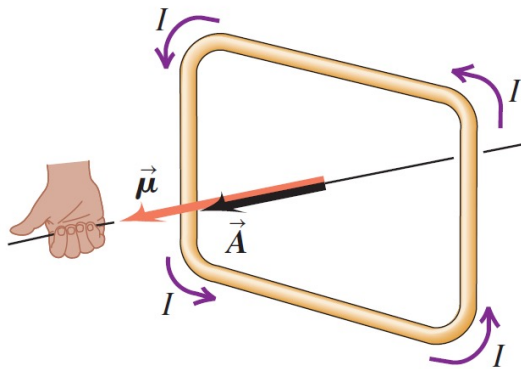
$$\tau = IBA \sin \phi$$

Current
Area of loop
Magnetic-field magnitude
Angle between normal to loop plane and field direction

Magnetic Dipole: $\mu = IA$

$$\tau = \mu B \sin \phi$$

Vector Magnetic Dipole: $\vec{\mu} = IA\vec{A}$



Vector magnetic torque on a current loop

$$\vec{\tau} = \vec{\mu} \times \vec{B}$$

Magnetic dipole moment
Magnetic field

The direction of $\vec{\tau}$ follows a **right-hand** rule.
(because of the cross product)

The direction of $\vec{\mu}$ follows a **right-hand** rule.

Potential Energy of a Current Loop

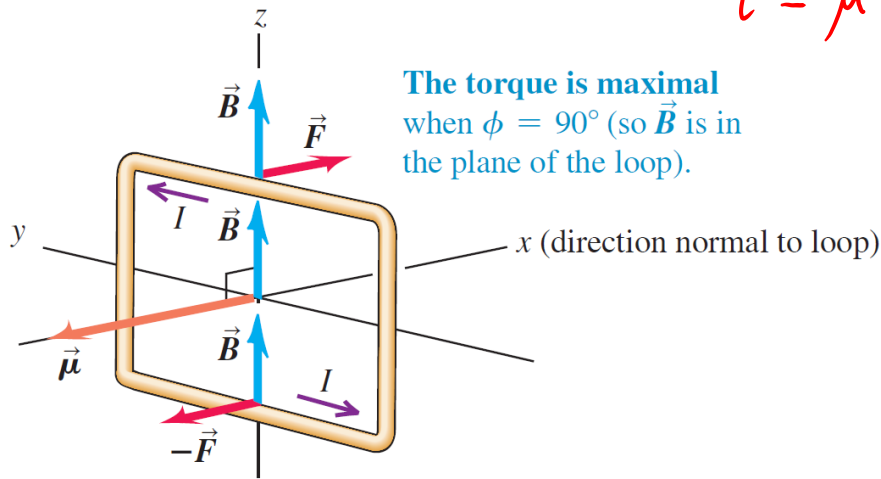
As the loop rotates due to the torque, the magnetic field does **work** on the loop.

Potential energy for a magnetic dipole in a magnetic field

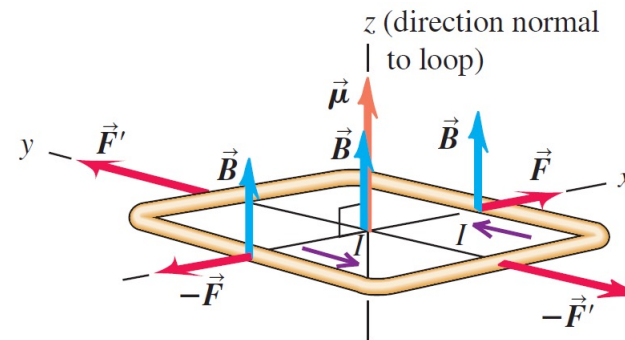
$$U = -\vec{\mu} \cdot \vec{B} = -\mu B \cos \phi$$

Magnetic dipole moment $\vec{\mu}$ (indicated by a dotted arrow pointing to the term $-\vec{\mu}$)
 Angle between $\vec{\mu}$ and \vec{B} (indicated by a dotted arrow pointing to the term ϕ)
 Magnetic field \vec{B} (indicated by a dotted arrow pointing to the term \vec{B})

$$\vec{\tau} = \vec{\mu} \times \vec{B} = \mu B \sin \phi$$



The potential energy is zero.



The loop is in stable equilibrium when $\phi = 0^\circ$; it is in unstable equilibrium when $\phi = 180^\circ$.

The potential energy is maximal.

Example

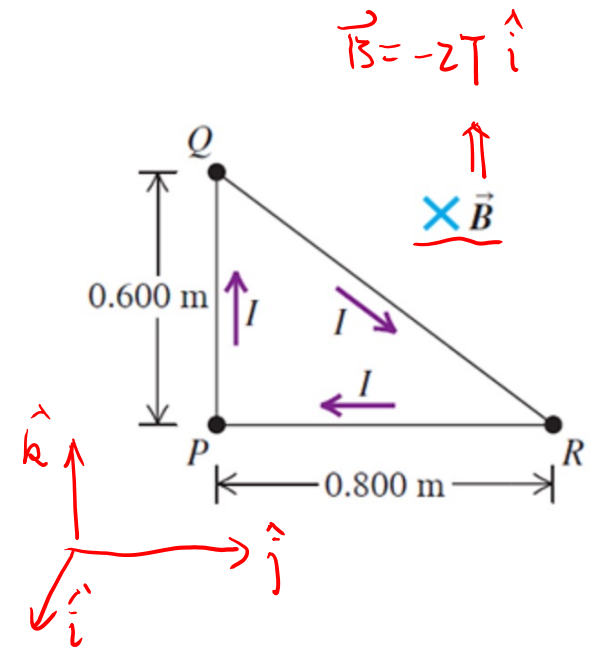
The loop of wire shown in forms a right triangle and carries a current $I = 5\text{ A}$ in the direction shown. The loop is in a uniform magnetic field that has magnitude $B = 2\text{ T}$ directed into the screen.

Find the net Force exerted by the magnetic field. $\Rightarrow 0$

Find the net torque on the loop.

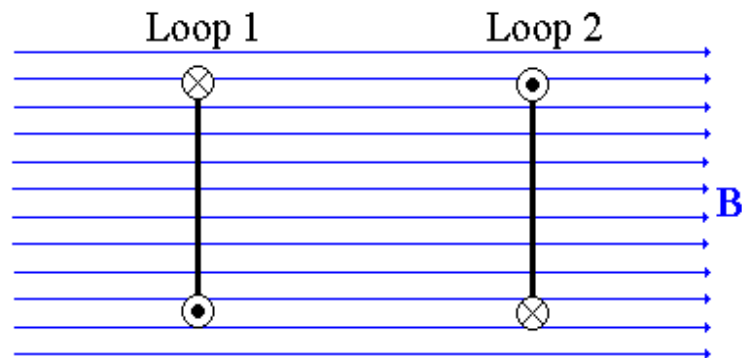
$$\begin{aligned}\vec{\tau} &= \vec{\mu} \times \vec{B} \\ \vec{\mu} &= I \vec{A} = (5\text{ A}) \frac{1}{2} (0.6\text{ m}) \times (0.8\text{ m}) (-\hat{i}) \\ &= (- \dots) \underbrace{(-\hat{i}) \times (-\hat{i})}_{0} \\ &= 0\end{aligned}$$

$$\vec{B} \sim (-\hat{i})$$



Two current carrying loops are oriented in a uniform magnetic field. The loops are nearly identical, except the direction of current is reversed. Which loop has a smaller potential energy?

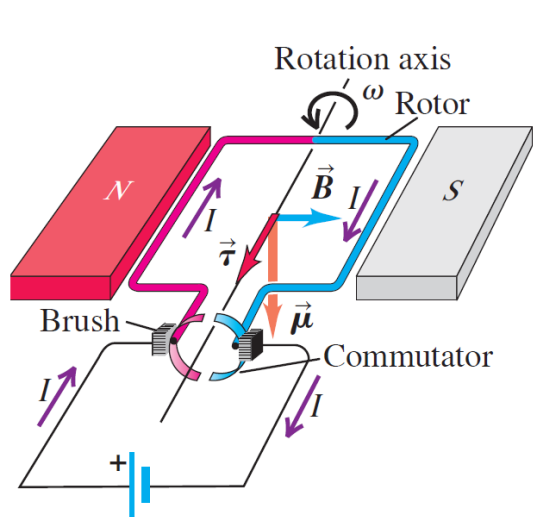
- A. Loop 1
- ✓ B. Loop 2
- C. Same



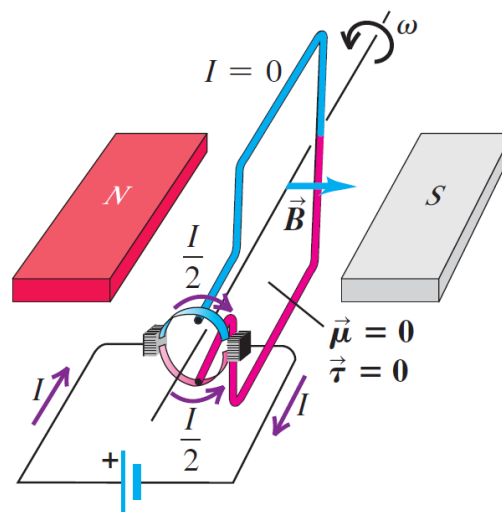
$$U = -\vec{\mu} \cdot \vec{B}$$

Direct Current Motor

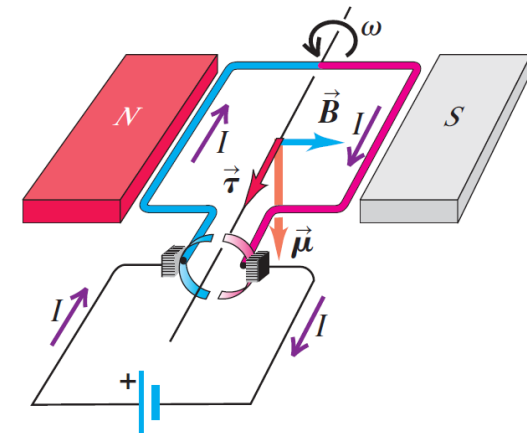
The rotor is a wire loop that is free to rotate about an axis; the rotor ends are attached to the two curved conductors that form the commutator.



- Current flows into the red side of the rotor and out of the blue side.
- Therefore the magnetic torque causes the rotor to spin counterclockwise.



- Each brush is in contact with both commutator segments, so the current bypasses the rotor altogether.
- No magnetic torque acts on the rotor.



- The brushes are again aligned with commutator segments. This time the current flows into the blue side of the rotor and out of the red side.
- Therefore the magnetic torque again causes the rotor to spin counterclockwise.