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**Department of Mathematics – University of Tennessee****Math 251 Matrix Algebra I****Test 1 Practice**

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Name: Solutions

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**Time allowed: 50 minutes****Instructions:**

- Calculators are not allowed.
- All electronic devices must be put away.
- Answers with insufficient or incorrect working will not receive full credit.
- Simplify answers whenever possible.

Page	Points	Score
2	10	
3	10	
4	10	
5	10	
6	10	
Total:	50	

1. (10 pts) Decide whether each statement is TRUE or FALSE. *No justification is required.*

- Every homogeneous linear system is consistent.

True.

- The matrix  $\begin{bmatrix} 1 & 3 & 0 \\ 0 & 1 & 1 \end{bmatrix}$  is in row echelon form.

True. (this is row echelon form, but not reduced row echelon form)

- If  $A$  and  $B$  are square matrices of the same size, then  $(A + B)^2 = A^2 + 2AB + B^2$ .

False.  $((A+B)^2 = A^2 + AB + BA + B^2.)$

- If  $AB$  is defined for matrices  $A$  and  $B$ , then  $(AB)^T = B^T A^T$ .

True.

- If  $A$  and  $B$  are invertible matrices of the same size, then  $A + B$  is invertible.

False. (eg.  $A=I$  and  $B=-I$  are invertible, but  $A+B=0$  is not invertible.)

- Every elementary matrix is invertible.

True.

- If  $A$  is invertible, and a multiple of the first row of  $A$  is added to the second row of  $A$ , then the resulting matrix is invertible.

True. (elementary row operations do not affect invertibility)

- It is impossible for a system of linear equations to have exactly two solutions.

True.

- The transpose of an upper triangular matrix is upper triangular.

False. (this results in a lower triangular matrix)

- If  $\vec{b}$  is a non-zero vector, then  $T(\vec{x}) = \vec{x} + \vec{b}$  is a linear transformation.

False. ( $T$  is neither homogeneous nor additive)

2. (8 pts) Use the Gauss-Jordan elimination algorithm to solve the linear system.

$$2x + 6y - 4z = 2$$

$$y + 2z = 1$$

$$x + 5y + 2z = 3$$

$$\left[ \begin{array}{ccc|c} 2 & 6 & -4 & 2 \\ 0 & 1 & 2 & 1 \\ 1 & 5 & 2 & 3 \end{array} \right]$$

$$\downarrow R_1 \rightarrow \frac{1}{2} R_1$$

$$\left[ \begin{array}{ccc|c} 1 & 3 & -2 & 1 \\ 0 & 1 & 2 & 1 \\ 1 & 5 & 2 & 3 \end{array} \right]$$

$$\downarrow R_3 \rightarrow R_3 - R_1$$

$$\left[ \begin{array}{ccc|c} 1 & 3 & -2 & 1 \\ 0 & 1 & 2 & 1 \\ 0 & 2 & 4 & 2 \end{array} \right]$$

$$\downarrow R_3 \rightarrow R_3 - 2R_2$$

$$\left[ \begin{array}{ccc|c} 1 & 3 & -2 & 1 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$\downarrow$$

$$\begin{array}{c} \vdots \\ \downarrow \\ R_1 \rightarrow R_1 - 3R_2 \end{array} \left[ \begin{array}{ccc|c} 1 & 0 & -8 & -2 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right].$$

Let  $z = t$ . Then:

$$\begin{array}{l} x = -2 + 8t, \\ y = 1 - 2t, \\ z = t. \end{array}$$

3. (2 pts) Suppose that the augmented matrix for a linear system with variables  $x_1, x_2, x_3, x_4$  has been reduced to the matrix below using elementary row operations. Write down the solution to the system.

$$\left[ \begin{array}{cccc|c} 1 & 0 & -3 & -1 & 2 \\ 0 & 1 & 1 & 0 & 4 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

Let  $x_3 = s$ ,  $x_4 = t$ . Then:

$$\begin{array}{l} x_1 = 2 + 3s + t \\ x_2 = 4 - s \\ x_3 = s \\ x_4 = t \end{array}$$

4. (10 pts) Let  $A = \begin{bmatrix} 1 & -1 & 3 \\ 2 & 0 & 4 \end{bmatrix}$  and  $B = \begin{bmatrix} 1 & 0 \\ -2 & 2 \end{bmatrix}$ . Simplify each expression below or explain why it is not possible.

(a)  $A + A^T =$  impossible.

$A$  is a  $2 \times 3$  matrix and  $A^T$  is a  $3 \times 2$  matrix.

Matrices can only be added if the dimensions are equal.

(b)  $A^2 =$  impossible.

You cannot multiply a  $2 \times 3$  matrix by a  $2 \times 3$  matrix.

Matrices can only be multiplied if the number of columns in the first matrix equals the number of rows in the second matrix.

(c)  $BA = \begin{bmatrix} 1 & 0 \\ -2 & 2 \end{bmatrix} \begin{bmatrix} 1 & -1 & 3 \\ 2 & 0 & 4 \end{bmatrix} = \begin{bmatrix} 1 & -1 & 3 \\ 2 & 2 & 2 \end{bmatrix}.$

(d)  $\text{tr}(3B) = \text{tr} \left( \begin{bmatrix} 3 & 0 \\ -6 & 6 \end{bmatrix} \right) = 3 + 6 = \underline{9}.$

(e)  $B^{-1} = \frac{1}{(1)(2) - (0)(-2)} \begin{bmatrix} 2 & 0 \\ 2 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 1 & \frac{1}{2} \end{bmatrix}.$

5. (6 pts) Consider the matrix equation

$$\begin{bmatrix} 2 & -5 & 8 \\ 0 & 3 & 4 \\ 0 & 0 & k^2 - 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 10 \\ -6 \\ k-1 \end{bmatrix}.$$

(a) For which value(s) of  $k$  are there an infinite number of solutions? Explain in complete sentences.

$k=1$ . This makes the last row/equation  $0=0$ , which gives a consistent system with one free variable.

(b) For which value(s) of  $k$  is the system inconsistent? Explain in complete sentences.

$k=-1$ . This makes the last row/equation  $0=-2$ , which gives an inconsistent system.

(c) For which value(s) of  $k$  is there a unique solution? Explain in complete sentences.

$k \neq \pm 1$ . This gives a consistent system with no free variables.

6. (4 pts) Find the inverse of the matrix below.

$$\begin{bmatrix} 1 & 0 & -2 & 0 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\left[ \begin{array}{cccc|cccc} 1 & 0 & -2 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 3 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right]$$

$$\downarrow R_2 \rightarrow R_2 - 3R_4$$

$$\left[ \begin{array}{cccc|cccc} 1 & 0 & -2 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 & 0 & -3 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 1 \end{array} \right]$$

$$\downarrow R_1 \rightarrow R_1 + 2R_3$$

$$\left[ \begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 1 & 0 & 2 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 & 0 & -3 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 1 \end{array} \right]$$

The inverse matrix is

$$\begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & 0 & -3 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

7. (5 pts) Suppose that the matrix transformation  $T_A$  is defined by

$$T_A(x_1, x_2, x_3) = (2x_1 - x_3, 4x_1, x_1 + x_2 + x_3, 5x_3).$$

- (a) What are the domain and codomain for the transformation?

The domain is  $\mathbb{R}^3$ .

The codomain is  $\mathbb{R}^4$ .

- (b) What is the standard matrix  $A$  for the transformation?

$$A = \begin{bmatrix} 2 & 0 & -1 \\ 4 & 0 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 5 \end{bmatrix}$$

8. (5 pts) Suppose that the matrix  $A$  satisfies the equation  $A^T A = A$ .

- (a) Prove that  $A$  is symmetric.

$$A^T = (A^T A)^T = A^T (A^T)^T = A^T A = A$$

Because  $A^T = A$ , the matrix  $A$  is symmetric.

- (b) Prove that  $A^2 = A$ .

$$A^2 = AA = A^T A = A.$$