## COSC 325: Introduction to Machine Learning

Dr. Hector Santos-Villalobos



### Lecture 12: Decision Trees





## **Class Announcements**

#### Homework:

Previous homework keys online Don't expect TA support during weekends.

Course Project: *Teaming issues.* 

#### Lectures:

On October 1<sup>st</sup>, no attendance record due to the Engineering Expo

#### **Exams:**

Exam #1: Thursday, 10/03

- Online
- Window 11 am to 1 pm
- 75 mins
- SDS accommodations set in Canvas.



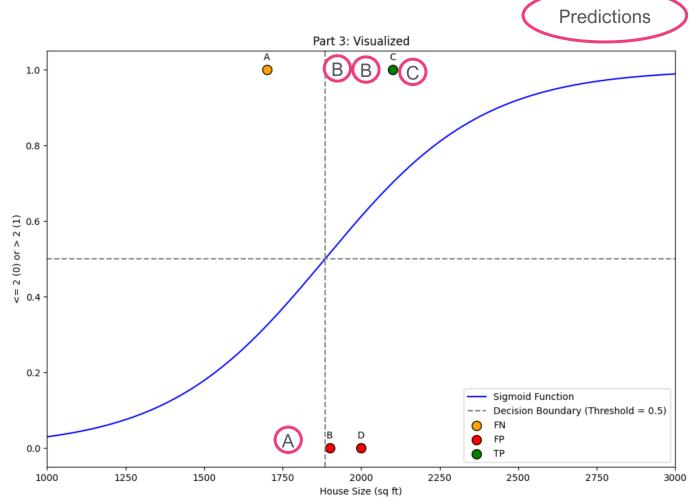
## Homework 2 Most Common Issue

True Values: A=1, B=0, C=1, D=0

•A: is a False Negative because the model predicted 0 but the actual class is 1.

•B and D: are False Positives because the model predicted 1, but the actual class is 0.

•C: is a True Positive because the model correctly predicted 1, which matches the actual class.

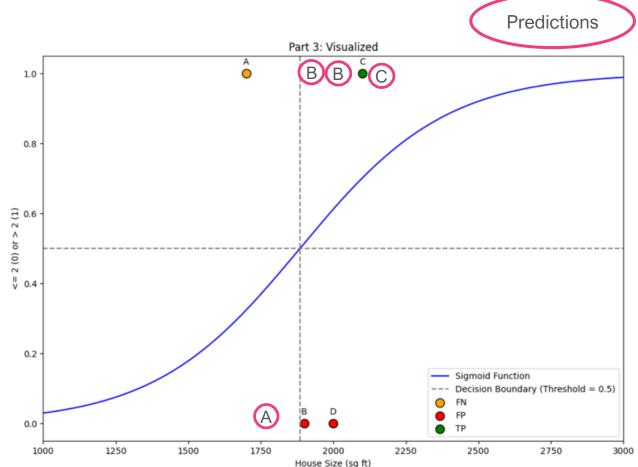




## **Confusion Matrix Intuition**

• Options: TP, TN, FP, FN

- Did the model make a mistake?
  - First letter: F
  - Otherwise, the first letter is T.
- Is the prediction Positive?
  - Second letter P.
  - Otherwise, the second letter is N.





#### Review

- Regularization techniques
  - L2 (ridge) Penalize large weights and reward weights smaller than one.
  - L1 (Lasso) Good for feature reduction.
  - ElasticNet Combines L2 and L1
  - Early stop Our last resource
- Decision Trees
  - Top-down iterative process
    - Select "best" feature
    - Ask a question on the feature to split data
    - Repeat steps on splits until purity or no new information for new splits.





## Pop Quiz

When considering the course material so far, which statement resonates with you the most?

A. I understand the ML concepts so far and can explain them in my own words.

B. I'm not completely sure about the ML concepts so far and doubt I could explain them.

**C.** I don't yet understand the ML concepts and cannot explain them.



## **Today's Topics**

**Decision Trees** 







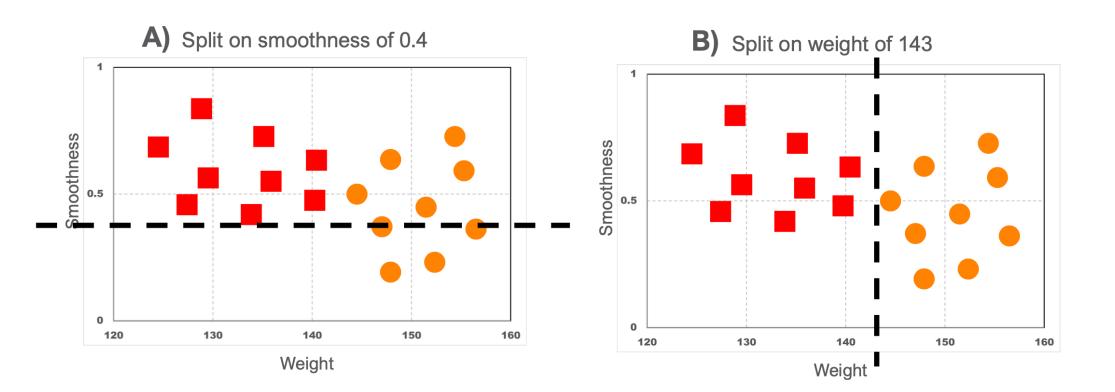
## **Splitting Criteria**



## Choosing the "best" attribute

- Key problem: choosing which attribute to split a given set of examples
- Some possibilities are:
  - Random: Select any attribute at random
  - Least-Values: Choose the attribute with the smallest number of possible values
  - Most-Values: Choose the attribute with the largest number of possible values
  - Max-Gain: Choose the attribute that has the largest expected information gain
    - i.e., the attribute that results in the smallest expected size of the subtrees rooted at its child nodes







*V*: Feature to split

 $D_p$ : dataset of parent node

$$IG(D_p, V) = I(D_p) - \sum_{j=1}^{m} \frac{N_j}{N_p} I(D_j)$$

 $D_j$ : dataset of child node j

*I*: Impurity measurement

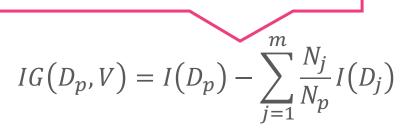
 $N_p$ : Number of training examples for parent node

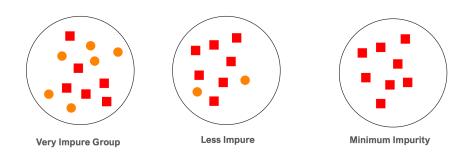
 $N_i$ : Number of training examples for child node j

*m*: Number of child nodes



If we have a <u>delta</u> between the parent node impurity and the child nodes cumulative impurity, we <u>gain</u> <u>information</u>.





*V*: Feature to split

- $D_p$ : dataset of parent node
- $D_j$ : dataset of child node j
- *I*: Impurity measurement
- $N_p$ : Number of training examples for parent node
- $N_j$ : Number of training examples for child node j

m: Number of child nodes

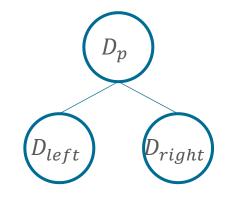


## **Information Gain: Binary Tree**

$$IG(D_p, V) = I(D_p) - \sum_{j=1}^{m} \frac{N_j}{N_p} I(D_j)$$

$$\begin{array}{c}
D_p\\
D_1\\
D_2\\
\end{array} \cdots \\
D_m
\end{array}$$

$$IG(D_p, V) = I(D_p) - \frac{N_{Left}}{N_p} I(D_{Left}) - \frac{N_{Right}}{N_p} I(D_{Right})$$



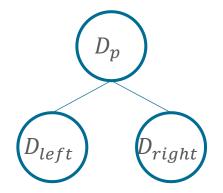


## **Information Gain: Binary Tree**

$$IG(D_p, V) = I(D_p) - \sum_{j=1}^{m} \frac{N_j}{N_p} I(D_j)$$

$$\begin{array}{c}
D_p\\
D_1\\
D_2\\
\end{array} \cdots \\
D_m
\end{array}$$

$$IG(D_p, V) = I(D_p) - \frac{N_{Left}}{N_p} I(D_{Left}) - \frac{N_{Right}}{N_p} I(D_{Right})$$
  
Let's define the impurity metric  
 $I(\cdot)$  to obtain some intuition  
about Information Gain.





## **Impurity Metrics**

- Entropy  $(I_H)$ :
  - Attempts to maximize mutual information.
  - How much knowledge about y we gain from knowing split  $D_j$ ?
- Gini (*I<sub>G</sub>*):
  - Minimizes the probability of misclassification
  - Produces very similar results to Entropy.
- Classification Error  $(I_E)$ :
  - Less sensitive to changes in the node class distribution
  - Useful when pruning the tree



p(D = i|t)

It is the proportion of the samples *D* in node *t* that belong to class *i*.

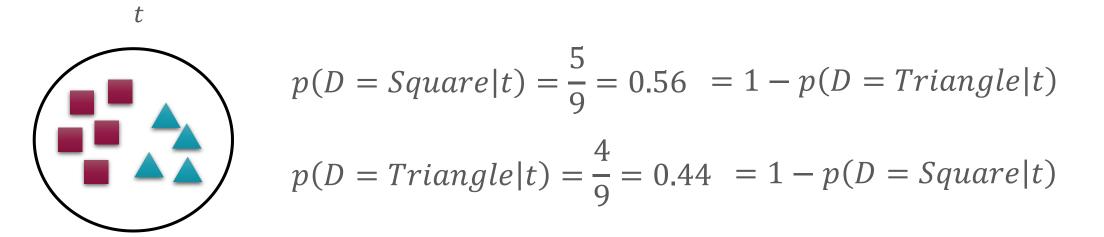
t  

$$p(D = Square|t) = \frac{5}{10} = 0.5$$
  
 $p(D = Triangle|t) = \frac{4}{10} = 0.4$   
 $p(D = Circle|t) = \frac{1}{10} = 0.1$ 



p(D = i|t) It is the proportion of the samples D in node t that belong to class i.

**Binary Node:** 





p(D = i|t) It is the proportion of the samples D in node t that belong to class i.

**Binary Node:** 

$$p(D = Square|t) = \frac{5}{9} = 0.56 = 1 - p(D = Triangle|t)$$

$$p(D = Triangle|t) = \frac{4}{9} = 0.44 = 1 - p(D = Square|t)$$

$$p = p(D = 1|t) \Rightarrow p(D = 0|t) = 1 - p$$



• From information theory—the higher the entropy the more information.

$$I_{H}(D,t) = -\sum_{i=1}^{c} p(D=i|t) \log_{2}(p(D=i|t))$$

p(D = i|t): Proportion of the samples *D* in node *t* that belong to class *i*.

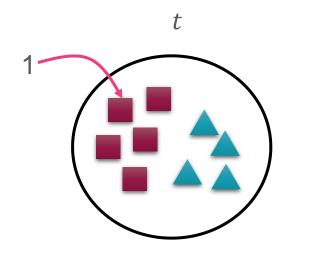
Binary node:



• From information theory—the higher the entropy the more information.

$$I_{H} = -p \log_{2}(p) - (1-p) \log_{2}(1-p)$$

*p*: Proportion of the samples that belong to the positive (1) class.



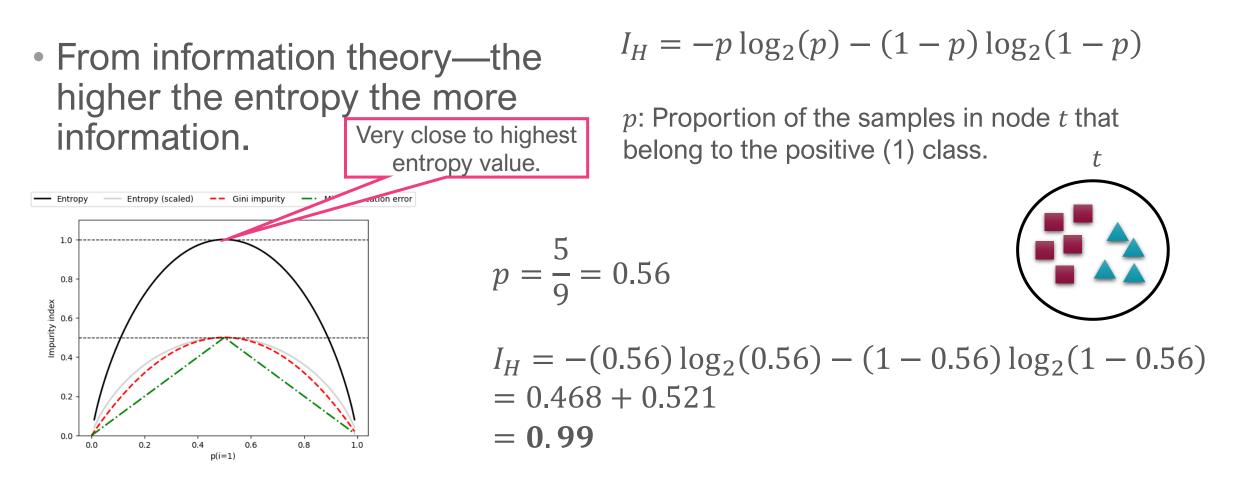
$$p = \frac{5}{9} = 0.56$$
  

$$I_H = -(0.56) \log_2(0.56) - (1 - 0.56) \log_2(1 - 0.56)$$
  

$$= 0.468 + 0.521$$
  

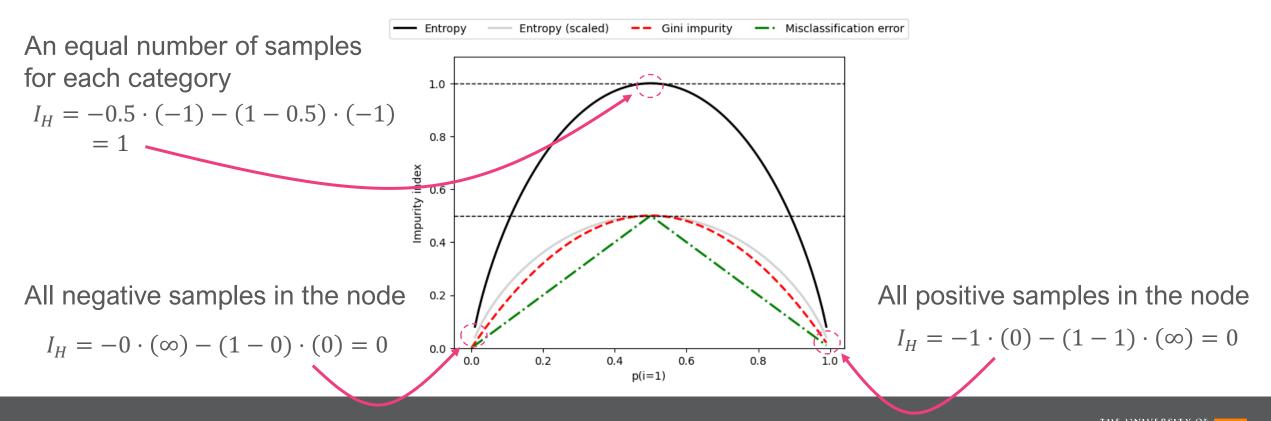
$$= 0.99$$







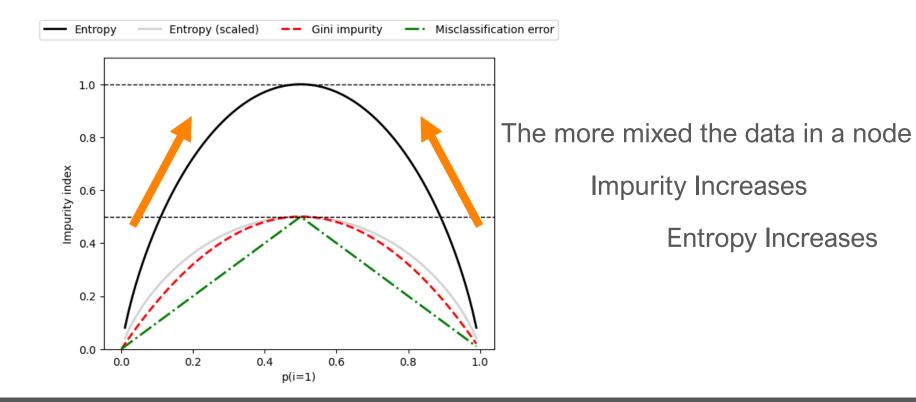
 $I_{H} = -p \log_{2}(p) - (1-p) \log_{2}(1-p)$ 





# Entropy (*I<sub>H</sub>*) - Shannon

 $I_{H} = -p \log_{2}(p) - (1-p) \log_{2}(1-p)$ 





## **Specific Conditional Entropy**

Now t = (V = v): The samples in the node meet certain criteria. E.g.,  $x_2 \le 2.5$ 

$$I_{H}(D|V = v) = -\sum_{i=1}^{m} p(D = i|V = v) \log_{2}(p(D = i|V = v)) = -p_{v} \log_{2}(p_{v}) - (1 - p_{v}) \log_{2}(1 - p_{v})$$

$$V = x_{j} \in \{A, B\}$$

$$Parent$$

$$V = A$$

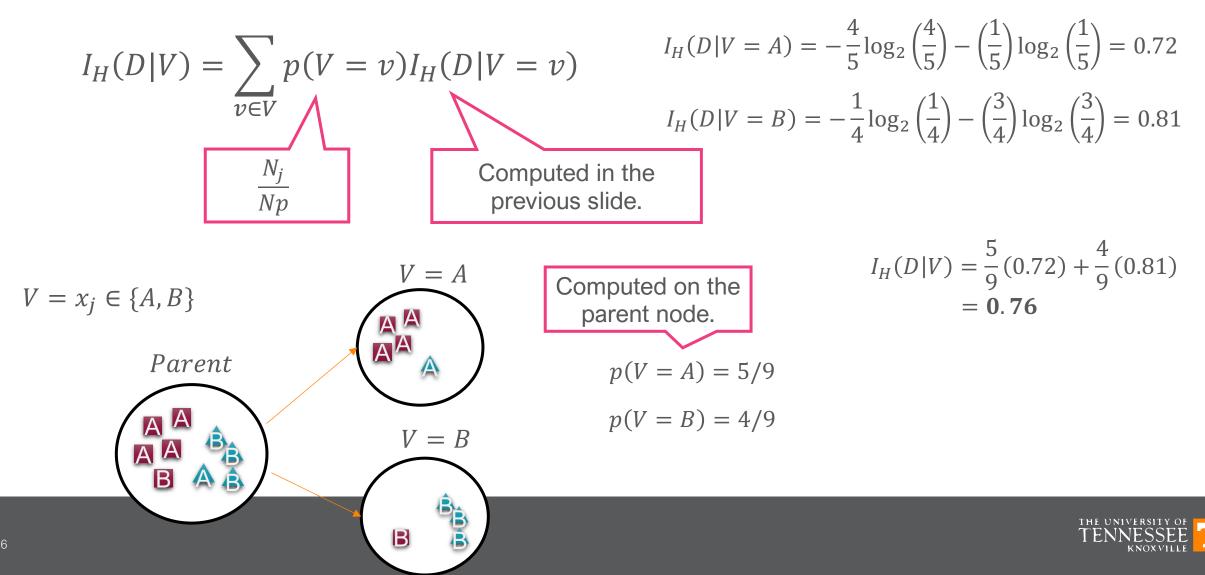
$$I_{H}(D|V = A) = -\frac{4}{5} \log_{2}\left(\frac{4}{5}\right) - \left(\frac{1}{5}\right) \log_{2}\left(\frac{1}{5}\right) = 0.722$$

$$V = B$$

$$I_{H}(D|V = B) = -\frac{1}{4} \log_{2}\left(\frac{1}{4}\right) - \left(\frac{3}{4}\right) \log_{2}\left(\frac{3}{4}\right) = 0.81$$



## **Conditional Entropy**



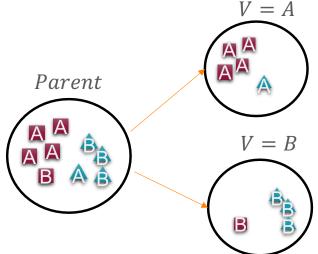
## **Mutual Information**

Mutual Information (*I*) is the amount of information that one random variable Y contains about another random variable X.

$$I(X,Y) = H(X) + H(Y) - H(X,Y)$$

 $H(X,Y) = H(Y) + H(X|Y) \Rightarrow$ 

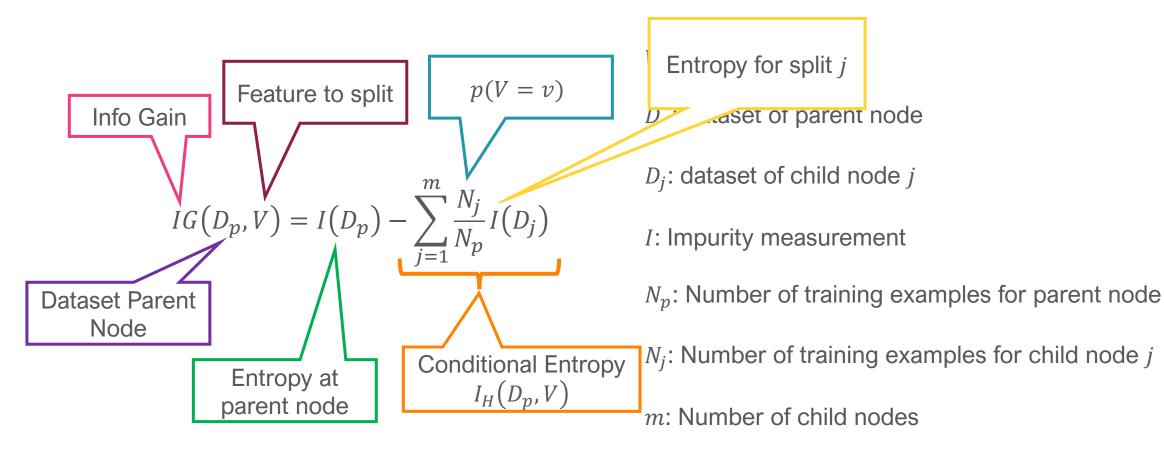
I(X,Y) = H(X) - H(X|Y)



$$I_H(D,V) = I_H(D) - I_H(D|V) = I_H(D) - \sum_{v \in V} p(V = v)I_H(D|V = v) = 0.99 - 0.76 = 0.23$$

This is our information gain.

KNOXVILL





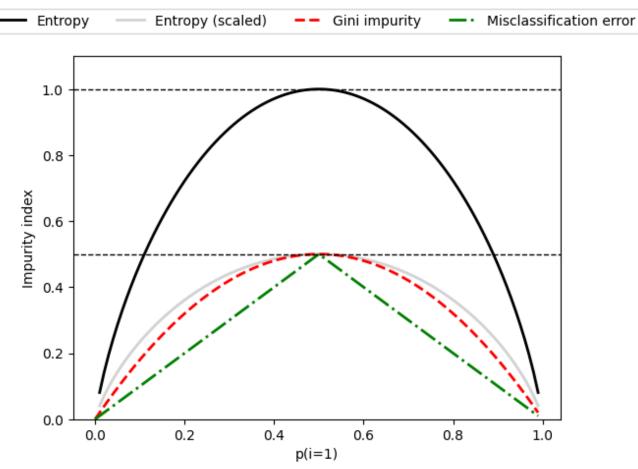
# **Other Impurity Metrics**

- Entropy  $(I_H)$
- Gini (*I*<sub>*G*</sub>)
- Classification Error  $(I_E)$

$$I_G(t) = \sum_{i=1}^{c} p(i|t) (1 - p(i|t)) = 1 - \sum_{i=1}^{c} p(i|t)^2$$

Binary node:

$$\begin{split} I_G(t) &= 1 - p(1|t)^2 - p(0|t)^2 \\ &= -2(p^2 - p) \end{split}$$





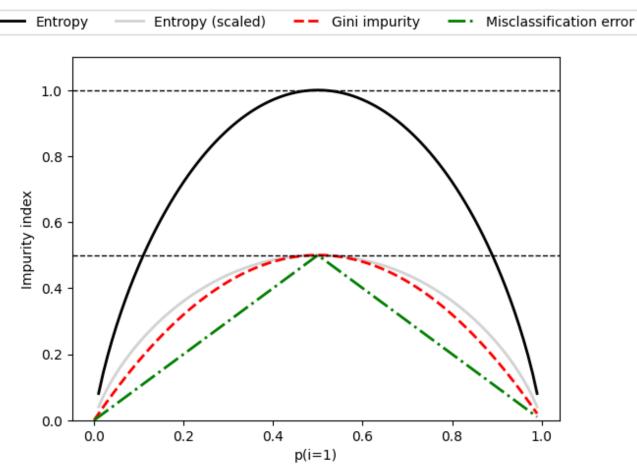
# **Other Impurity Metrics**

- Entropy  $(I_H)$
- Gini (*I*<sub>*G*</sub>)
- Classification Error (I<sub>E</sub>)

$$I_E = 1 - \max_{i \in c} \{ p(i|t) \}$$

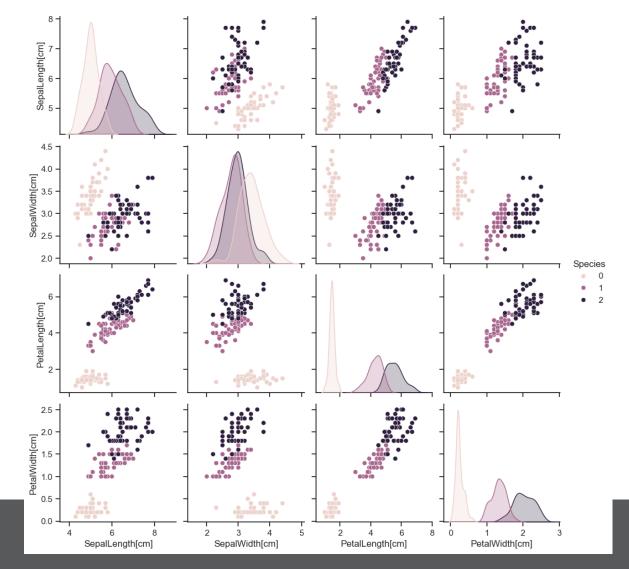
Binary node:

$$I_E = 1 - \max\{p, 1 - p\}$$



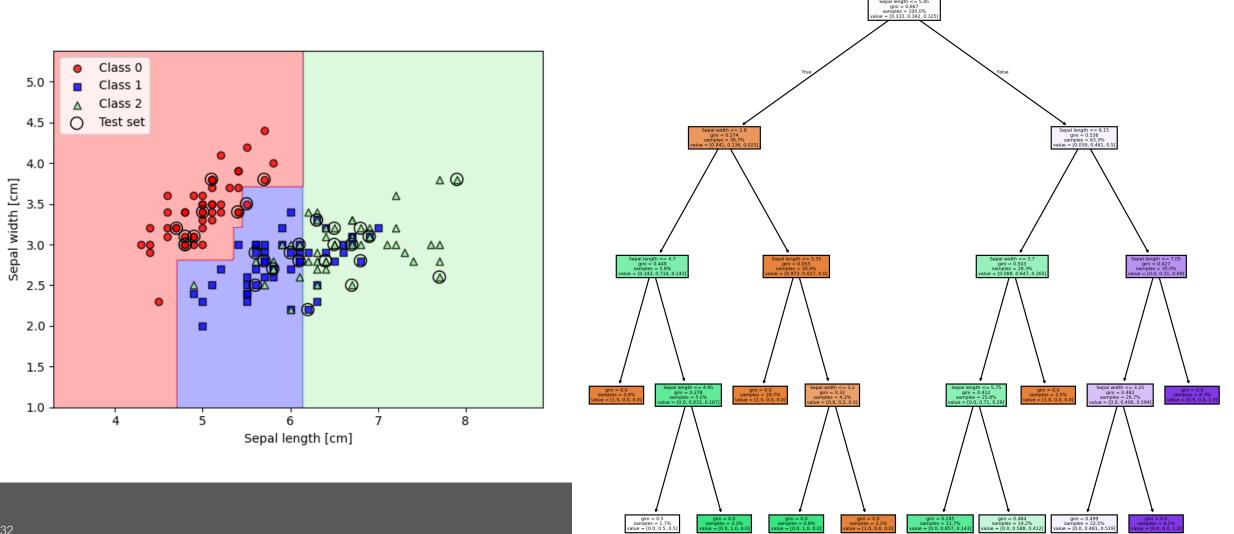


### **Demo with Iris dataset**

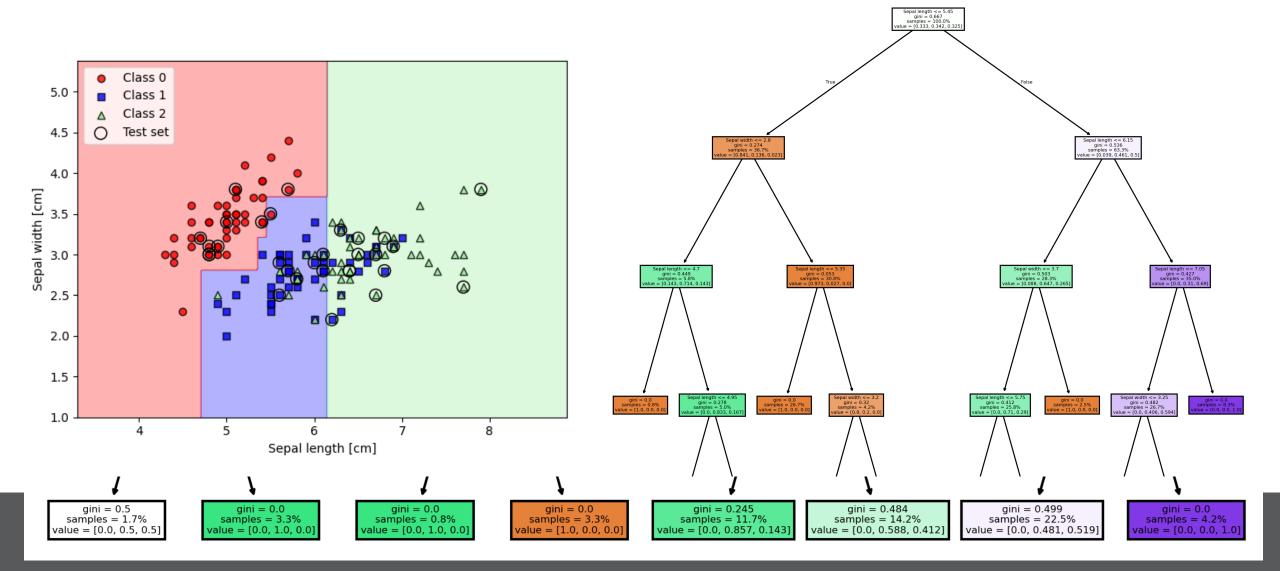




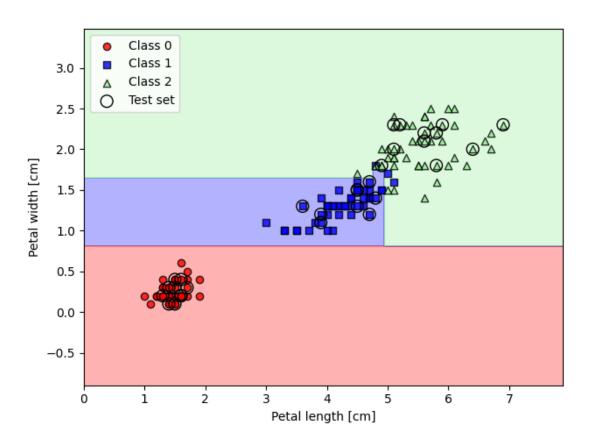
### **Demo with Iris dataset: Sepal Width and Length**

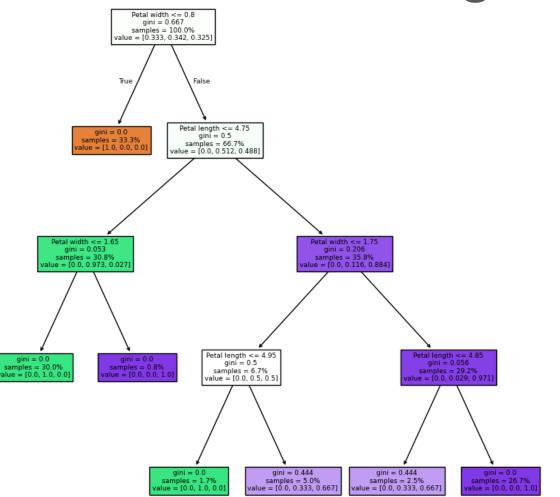


### **Demo with Iris dataset: Sepal Width and Length**



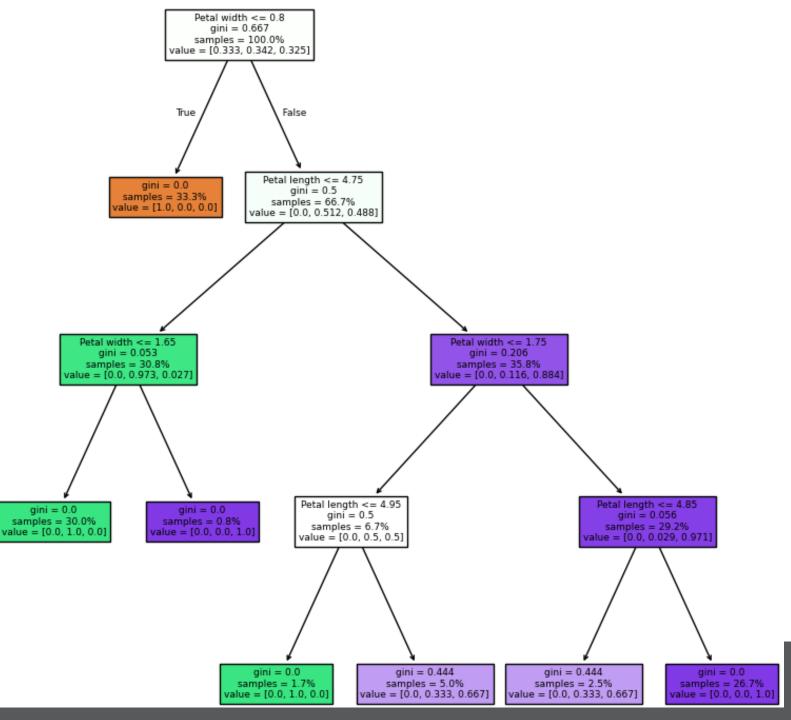
### **Demo with Iris dataset: Petal Width and Length**







### Demo with Iris dataset: All Features

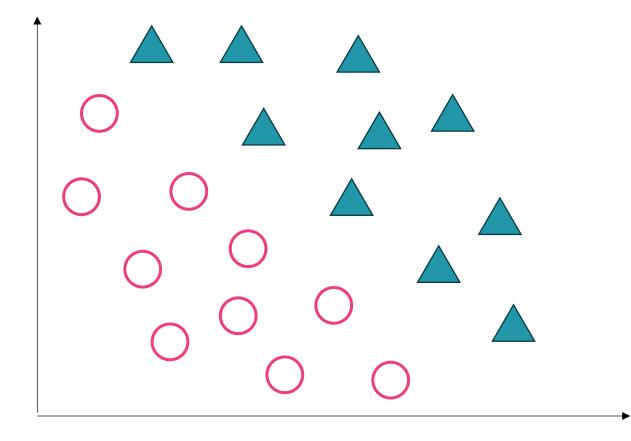


## **Decision Trees Shortcomings**





## **Diagonal Boundaries**

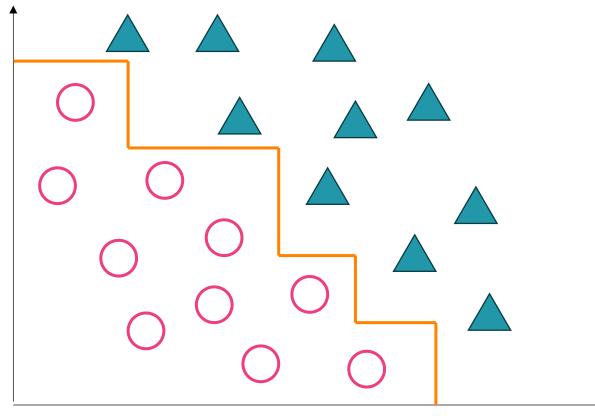




# **Diagonal Boundaries** $\hat{y} = X\theta$



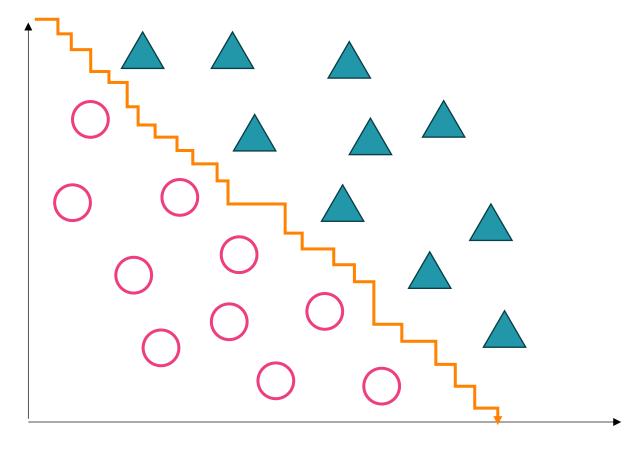
## **Diagonal Boundaries**



An internal node for each segment.

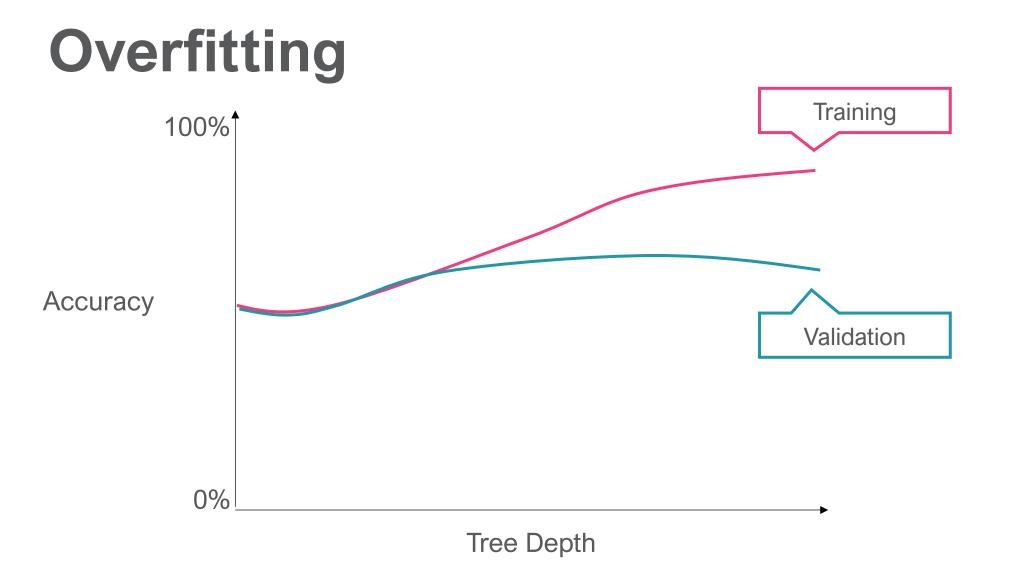


## **Diagonal Boundaries**



Tree will become too large.







## **Pop Quiz**

Why (when) does the accuracy start at ~50% for a binary decision tree?

A. 100% of samples are from the positive class

**B.** 100% of samples are from the negative class

**C.** 50% of samples are from the positive class.

**D.** 50% of the samples are easy to classify.



## **Pop Quiz**

Why (when) does the accuracy start at ~50% for a binary decision tree?

**A.** 100% of samples are from the positive class

**B.** 100% of samples are from the negative class

C. 50% of samples are from the positive class.

**D.** 50% of the samples are easy to classify.



## **Gain Ratio**

- Addresses wide trees and helps with overfitting
- Penalizes node splits for features with several categories
  - E.g., Date column
- When the number of child nodes is 10x, SplitInfo is 2x

 $GainRatio(\mathcal{D}, V) = \frac{Gain(\mathcal{D}, V)}{SplitInfo(\mathcal{D}, V)}$ 

$$SplitInfo(\mathcal{D}, V) = -\sum_{v \in V} \frac{|\mathcal{D}_v|}{|\mathcal{D}|} \log_2\left(\frac{|\mathcal{D}_v|}{|\mathcal{D}|}\right)$$



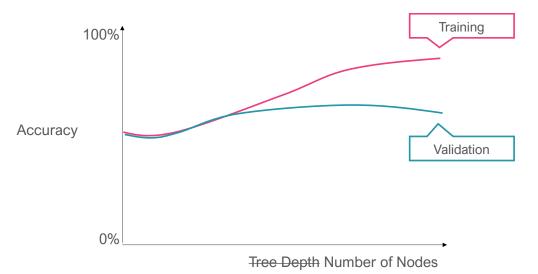
# Pre-Pruning (Before we grow tree)

- Set a depth cut-off (maximum tree depth)
- Cost-complexity pruning, where we set a total number of nodes.
- Stop growing if split is not statistically significant (e.g.,  $\chi^2$  test)
- Set a minimum number of data points for each node
  - Addresses labeling errors
- Remove irrelevant attributes



# **Post-Pruning (After Training)**

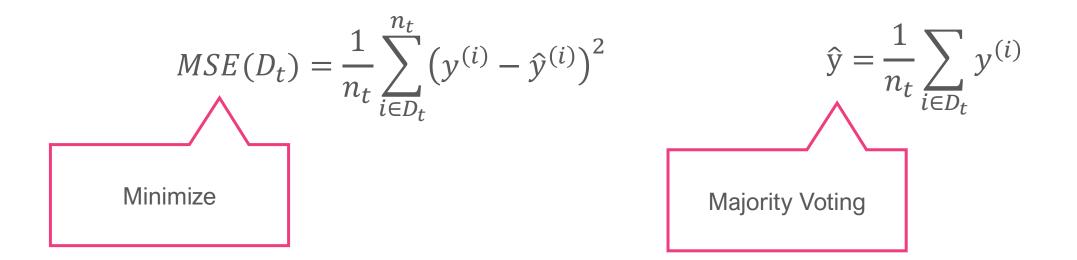
- Acquire more training data
- Grow full tree first, then remove nodes
- Reduced-error pruning: remove nodes via validation set evaluation
  - Requires a test set
  - Greedly remove node that most improves validation set accuracy





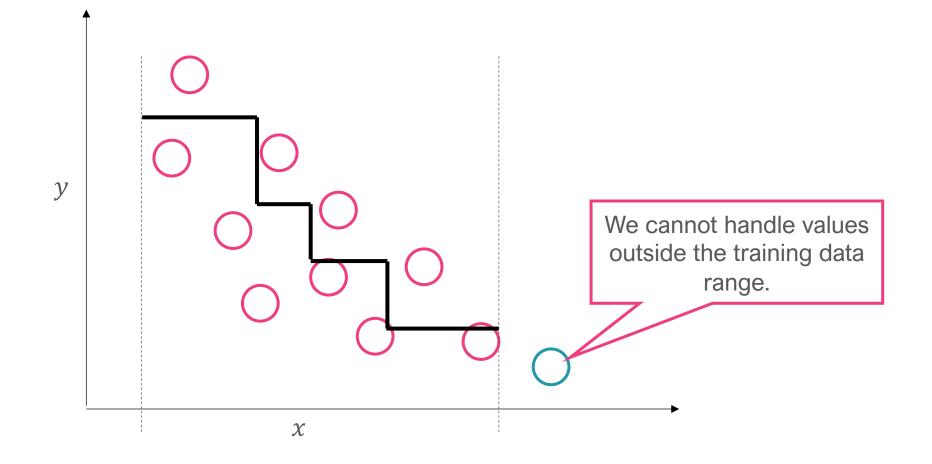
## **Regression Trees**

- Variance reduction (CART algorithm)
- Given a node *t*





## **Shortcomings in Tree Regression**





## **ID3 – Iterative Dichotomizer**

- Early algorithm proposed by Quinlan, 1986.
- Cannot handle numeric values
- Prone to overfitting (no pruning)
- Produce short and wide trees
- Maximize information gain by minimizing entropy
- Support discrete features, binary and multi-category features



## C4.5

- Continuous and discrete features, Quinlan 1993.
- Continuous is very expensive, because must consider all possible ranges
- Handles missing attributes (ignores them in gain compute)
- Post-pruning (bottom-up pruning)
- Gain Ratio stop criteria



## CART

- Classification And Regression Trees proposed by Breiman 1984.
- Handles continuous and discrete features
- Strictly uses binary splits (taller trees than ID3, C4.5)
- Trees produce better results that ID3 and C4.5 but are harder to interpret
- Tree growth
  - Variance reduction in regression trees
  - Gini impurity, also known as twoing.
- Cost complexity pruning



#### Review

- (+) Easy to interpret and communicate
- (+) Can represent "complete" hypothesis space
- (-) Easy to overfit
- (-) Elaborate pruning required
- (-) Expensive to just fit a "diagonal line"
- (-) Output range is bounded in regression trees by input range.





#### **Next Lecture**

• Ensemble techniques



